

# WIRELESS POWER TRANSFER FOR ELECTRIC VEHICLES

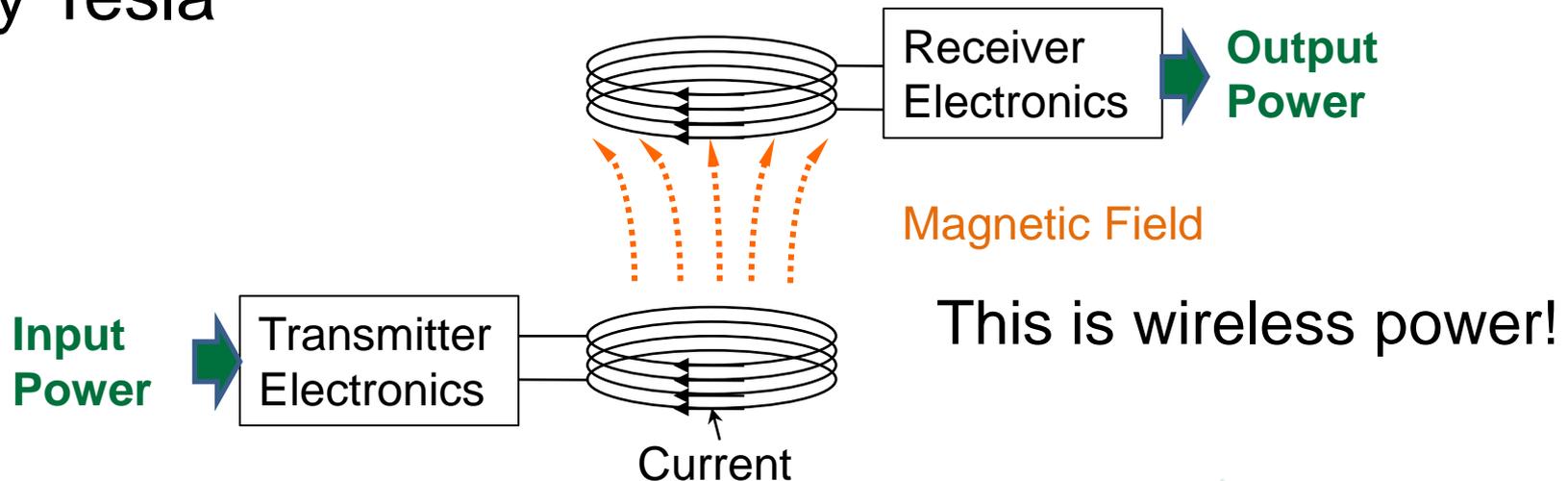
Hunter Wu, Ph.D

Energy Dynamics Laboratory (EDL)

Utah State University Research Foundation (USURF)

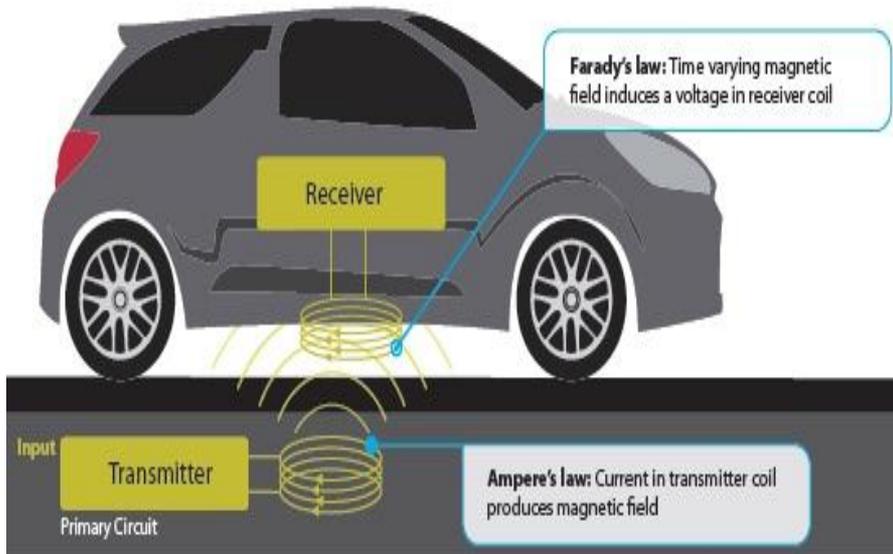
# What Is Wireless (Inductive) Power Transfer?

- ▶ IPT transfers electric power over an air gap
- ▶ Uses ampere's and faraday's law
  - Ampere: current in transmitter coil produces magnetic field
  - Faraday: magnetic field induces a voltage in receiver coil
- ▶ IPT concept not new – proposed over 100 years ago by Tesla



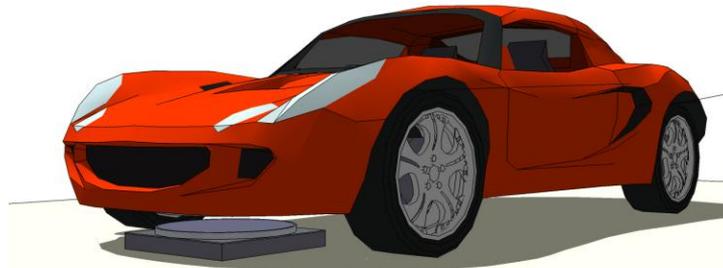
# Proposed Approaches

- ▶ High power stationary charging
- ▶ In-motion power transfer



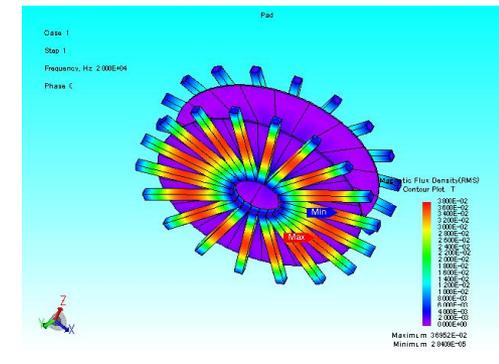
# High Power Stationary Charging

- ▶ High power levels
  - Achieve 30miles/min goal using 450kW
- ▶ Convenience – no user input
  - No wasted time to mate plug
- ▶ Maintenance free – solid state
- ▶ Weather proof
- ▶ Less efficient than conductive (>93%)
- ▶ Relative costs (?)



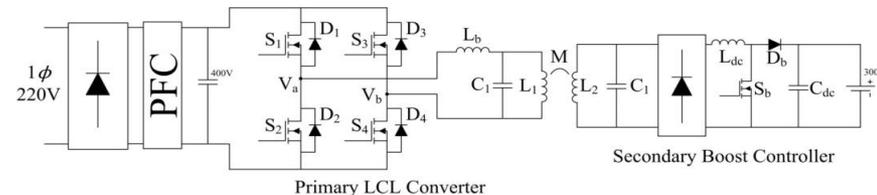
# Current Stationary Charging System

Parameters	Value	Notes
Power Level	5kW	Pad sized for 20kW
Frequency	20kHz	20 – 100kHz capabilities
Air gap	6 – 10.5 in	With maintained efficiency across range
Efficiency	> 90%	> 98% magnetic transfer
Voltage	300VDC	Output
Pad dimension	32-in diameter	
Pad weight	~ 45 lbs	Expect 2X reduction in future designs
Misalignment	8 in @ 6 in gap	With maintained efficiency (conical region)
EMF exposure	ICNIRP	Meets latest ICNIRP standards
Modularity	Scalable	Rapid design deployment



Pad simulation

- 5kW
- High efficiency
- Wide gap tolerance
- Meets safety standards



IPT System Topology

# High Power Charging Technology

## ► Power module development

- 1200V power high wideband gap devices
- Gate driver development

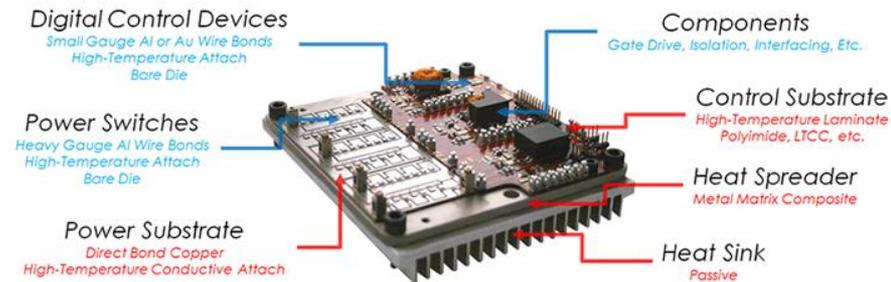


Photo credit: APEI

## ► IPT development

- Fixed frequency soft-switching
- New concepts for field shaping
- Active EMF cancellation
- Wide range coupling operation
- Paralleling inverters

# In-motion Power Transfer Benefits

▶ **Economic Security:** reduces dependence on:

- Foreign oil (currently \$300B per year)
- Rare Materials (lithium: 80% battery size reduction)

	Reserves	U.S.	Our Allies	Other Nations	
	Lithium	0.4%	8.1%	92%	Battery
	Copper	7.5%	14%	86%	
Ferrite	Iron	4.5%	20%	80%	WPT
	Manganese	-	19%	81%	
	Zinc	20%	44%	56%	

▶ **Relieves range anxiety, adds convenience, reduces battery size and increases battery life**

▶ **Cost [1,2]:** comparable with ICE and cheaper than battery EV

- The region around I-5 in Seattle, 80% electrification, 30 mile battery range and cost of \$2.7M per lane mile results in rough cost competitiveness with ICE vehicles

1. F. Risch, “Electrified roadway activities at the Bavarian technology center for electric drives”, Transportation Research Board, 26<sup>th</sup> January 2011, Washington DC

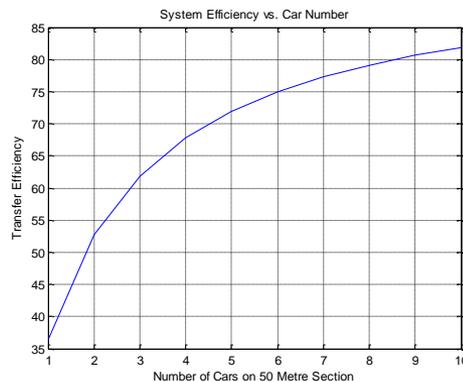
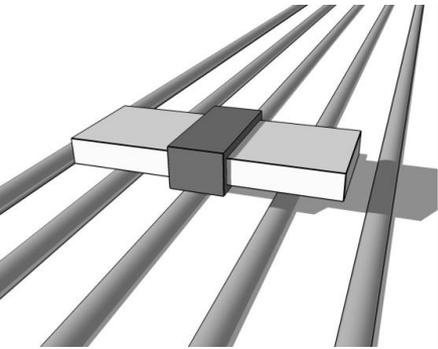
2. A. Brooker, M. Thornton and J. Rugh, “Technology improvement pathways to cost-effective vehicle electrification”, SAE 2010 World Congress and Exhibition, 12<sup>th</sup> April 2010, Detroit

# Challenges to In-Motion IPT

- ▶ **Challenge:** Achieve > 90% grid-to-vehicle transfer efficiency @ 75mph, 40kW and wide tolerance
- ▶ **Challenge:** Reduce cost of roadway electrification to ~\$2M/ lane mile

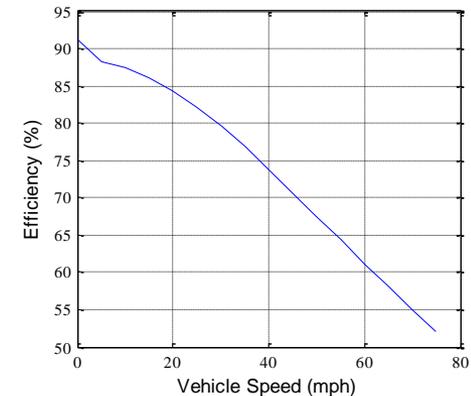
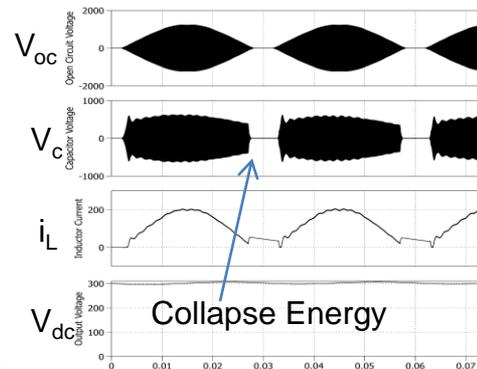
## Conventional Distributed IPT

- From [1],  $P = \omega I_1^2 Q_2 M^2 / L_2$
- $I_1 \sim 400-600A$
- Very high track losses (230-520W/m)
- Fields too high for humans
- Efficiency high only with 10 vehicles



## Stationary IPT

- Circular pad has power null at 80% of pad radius [2], only 46% usable
- Collapse of magnetic energy around power null causes losses



1. J. T. Boys, G. A. Covic and A. W. Green, "Stability and control of inductively coupled power transfer systems," *IEE Proceedings - Electric Power Applications*, vol. 147, no. 1, pp. 37-43, 2000.
2. M. Budhia, G. A. Covic and J. T. Boys, "Design and optimisation of magnetic structures for lumped Inductive Power Transfer systems," in *IEEE Energy Conversion Congress and Exposition, 2009. ECCE 2009.*, 2009, pp. 2081-2088.

# In-motion Technology

## ► Key Outcomes

- Eliminate range anxiety
- 40kW @ 75 mph,  $\eta > 90\%$
- <\$2M per lane mile

## ► Proposed Approach

- Magnetic field shaping
- Fast dynamic controllers
- Reactive VAR compensators
- Soft switching topologies
- High speed rotating test approach

Parameters	State of Art	Proposed System
Operation Speed	Stationary	>75mph
Power Level	Up to 6.6kW	30kW-50kW
Frequency	20kHz	20-140kHz
Air gap	Up to 10"	Up to 15"
Efficiency	> 90% (System)	> 90% (System)
Pad weight	~ 45 lbs	< 80 lbs
Misalignment	8" at 6" gap	10" at 15" gap
EMF exposure	ICNIRP	ICNIRP